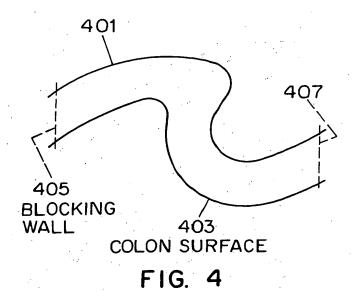


F1G. 2



501 START POINT

FIG. 5

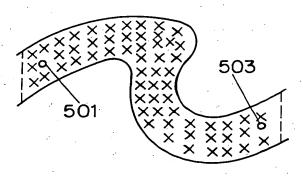


FIG. 6

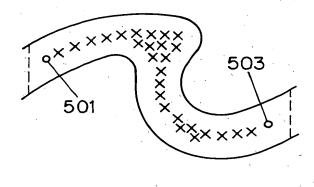


FIG. 7

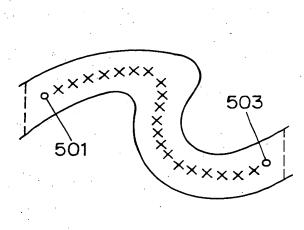


FIG. 8

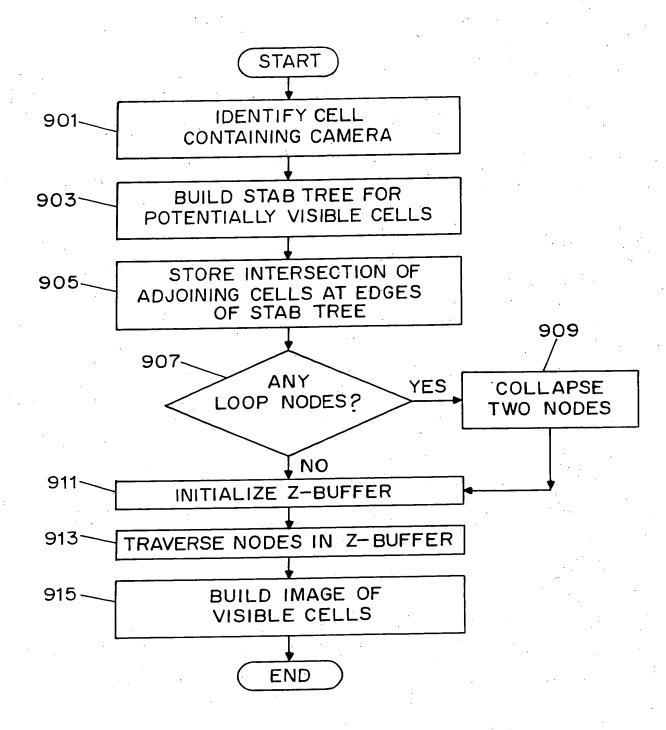


FIG. 9

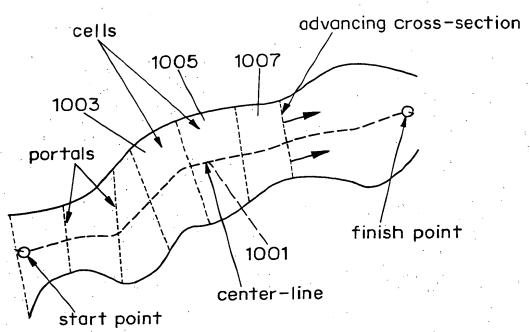


FIG. 10

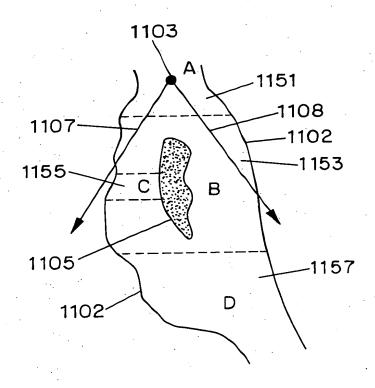


FIG. 11(a)

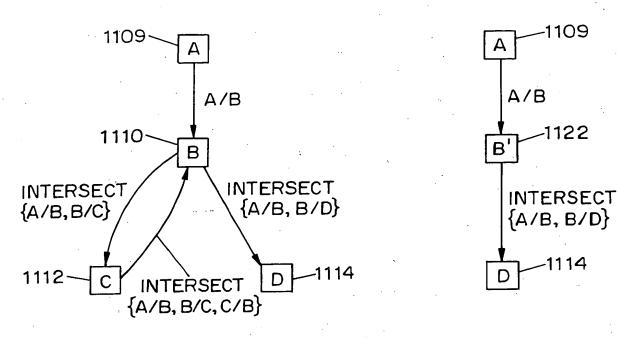


FIG. 11(b)

FIG. 11(c)

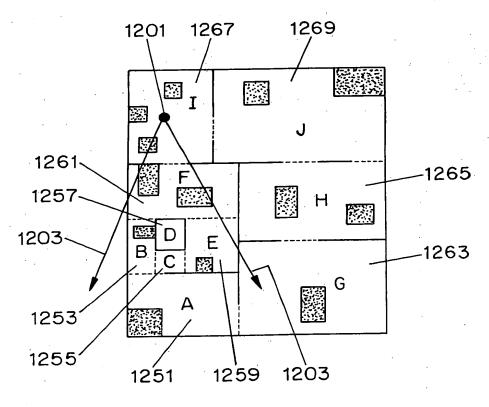
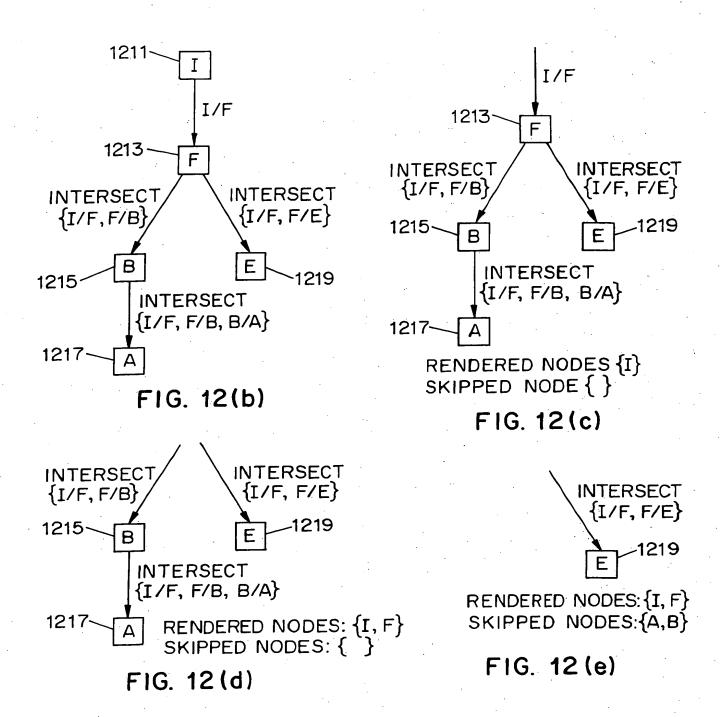
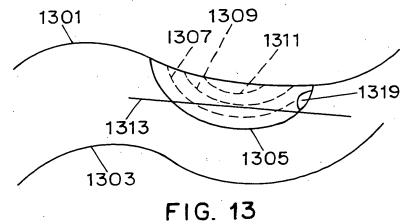


FIG. 12(a)





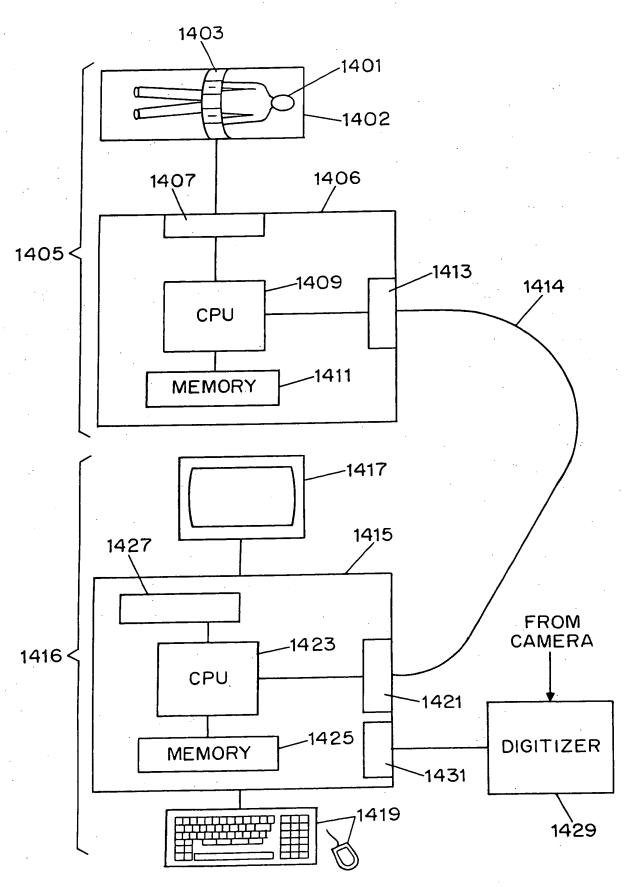
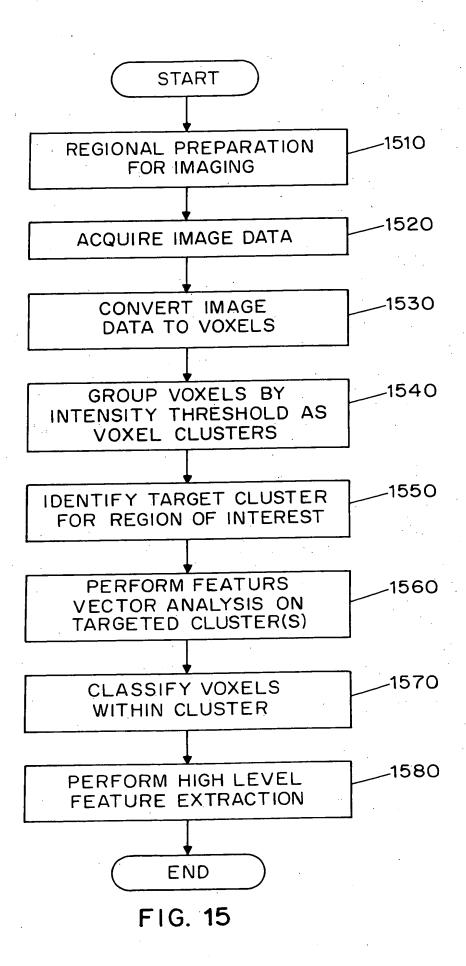


FIG. 14



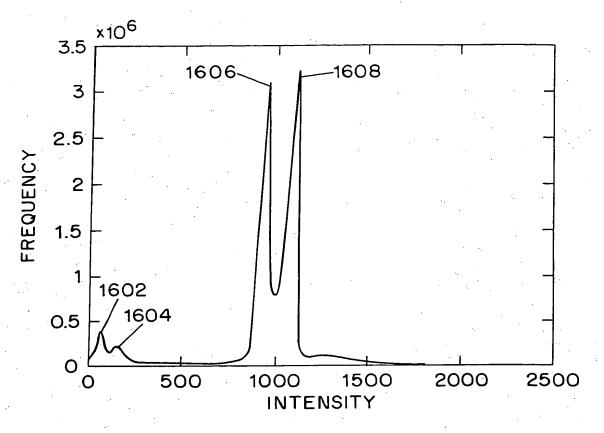


FIG. 16

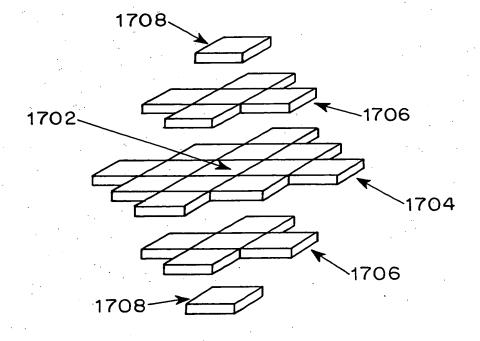


FIG. 17

1802

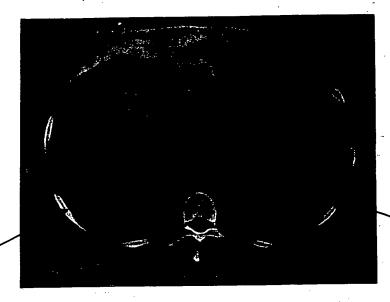


FIG. 18A

1802

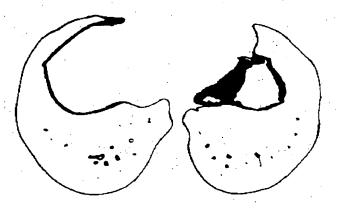


FIG. 18B

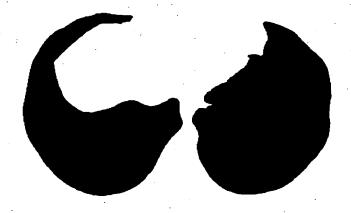


FIG. 18C

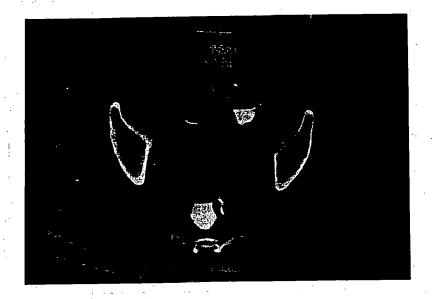


FIG. 19A

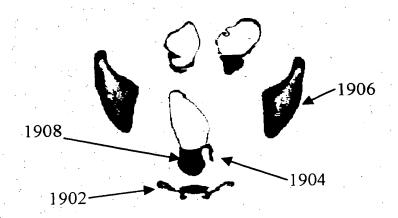


FIG. 19B



FIG. 19C

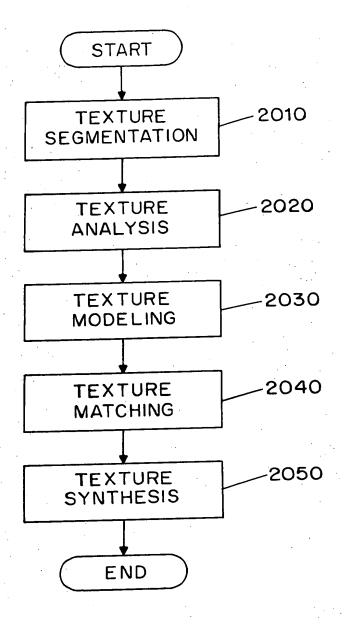


FIG. 20

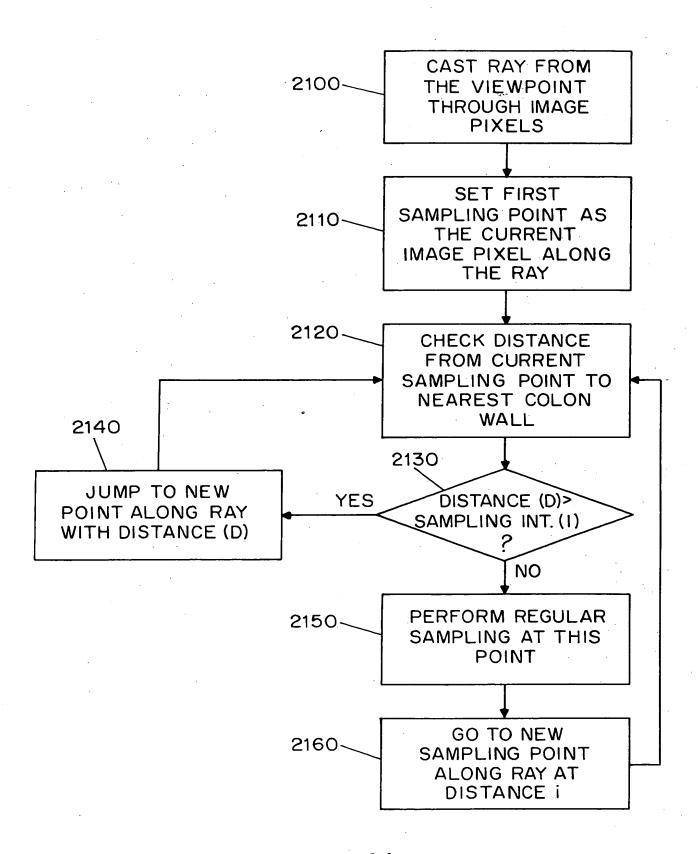


FIG. 21

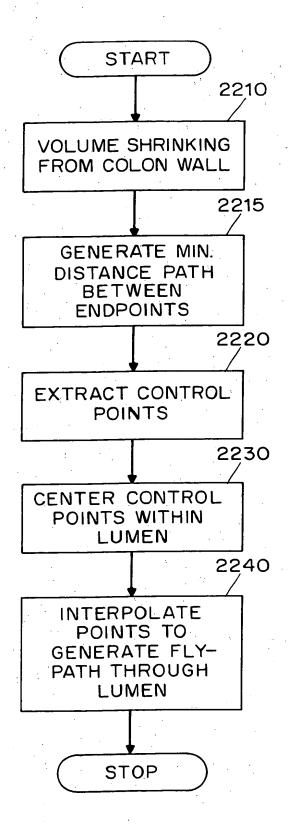


FIG. 22

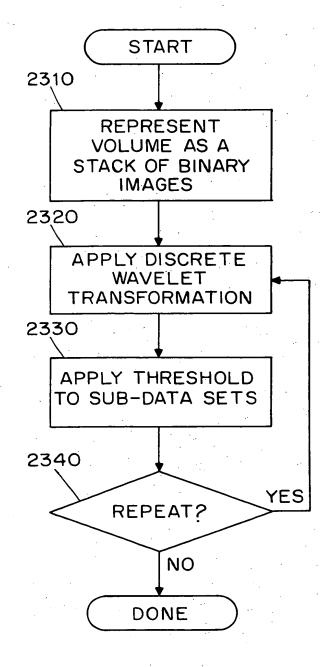
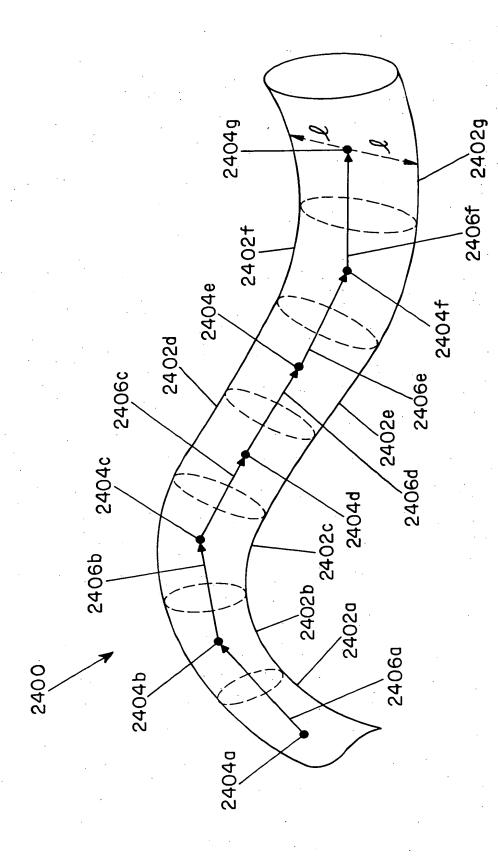


FIG. 23



F16. 24

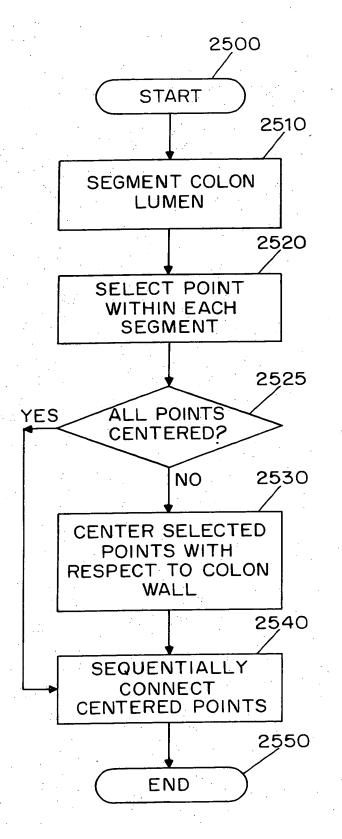


FIG. 25

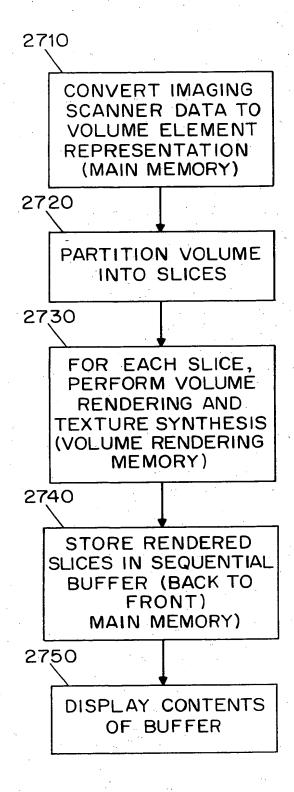
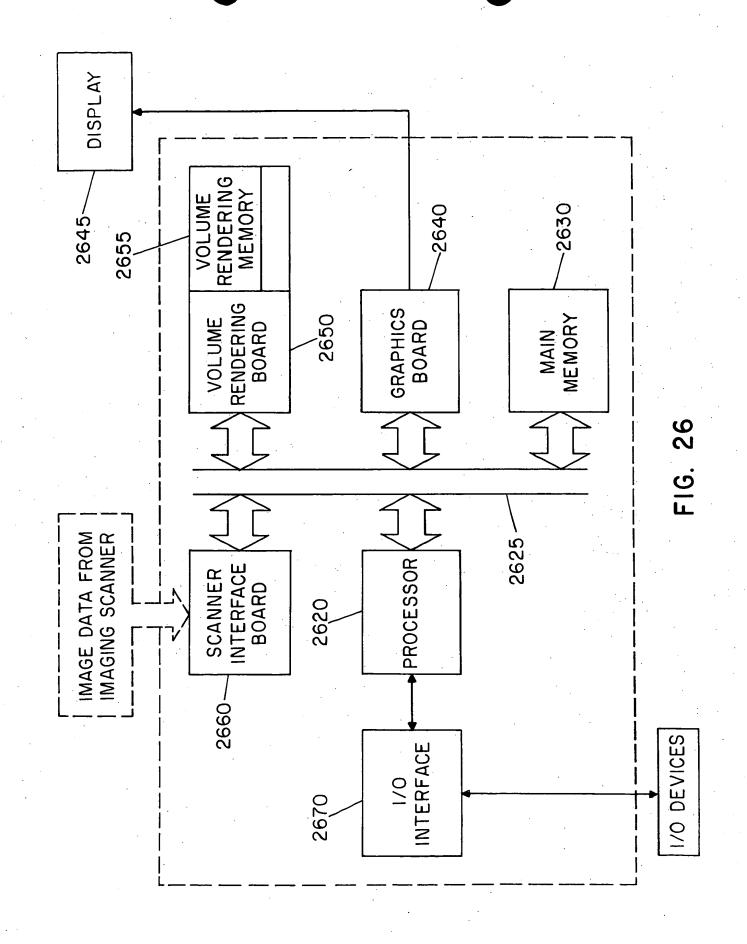
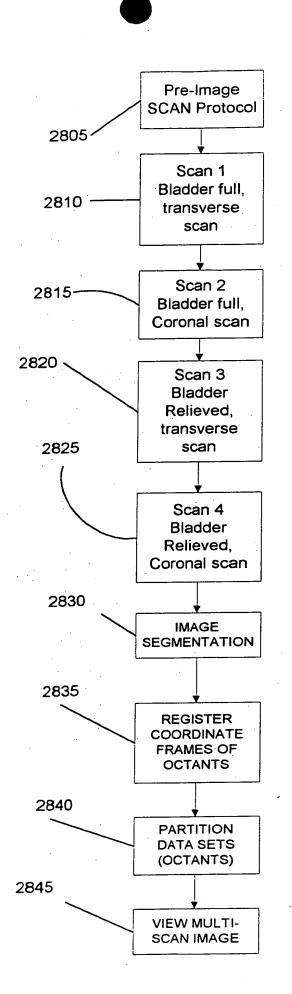


FIG. 27

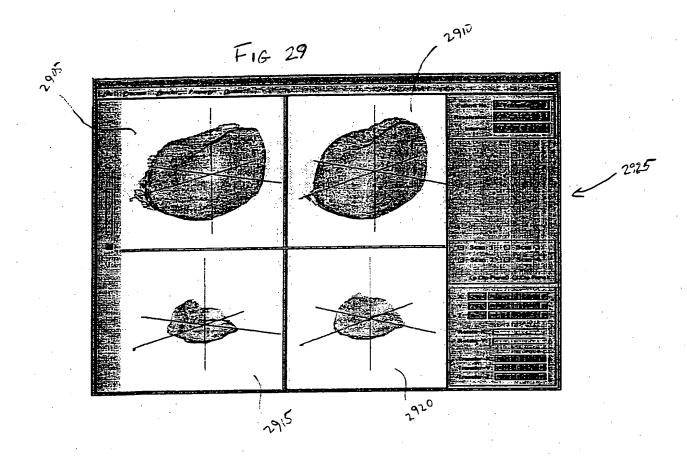




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F16 28



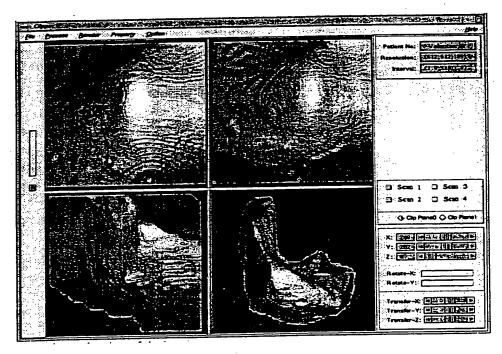


FIG. 30

FIG. 31

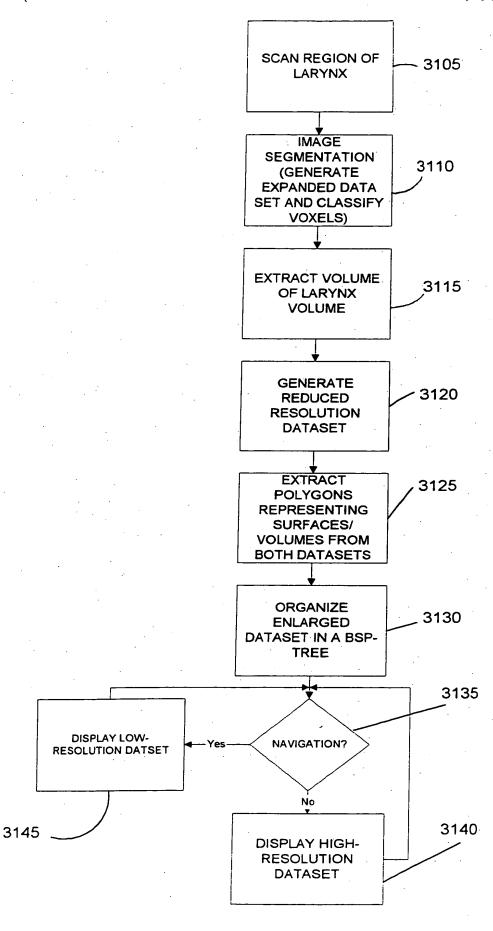


FIG. 32

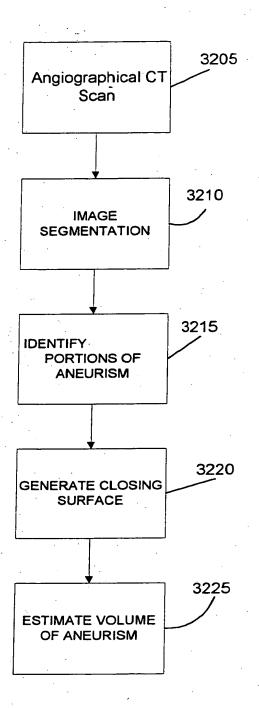
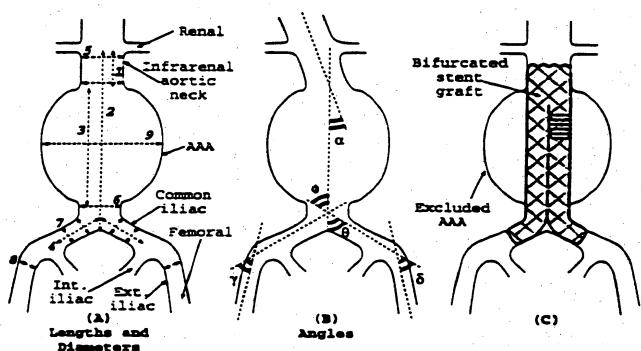


Fig. 334

Fig. 338

FIG 33C



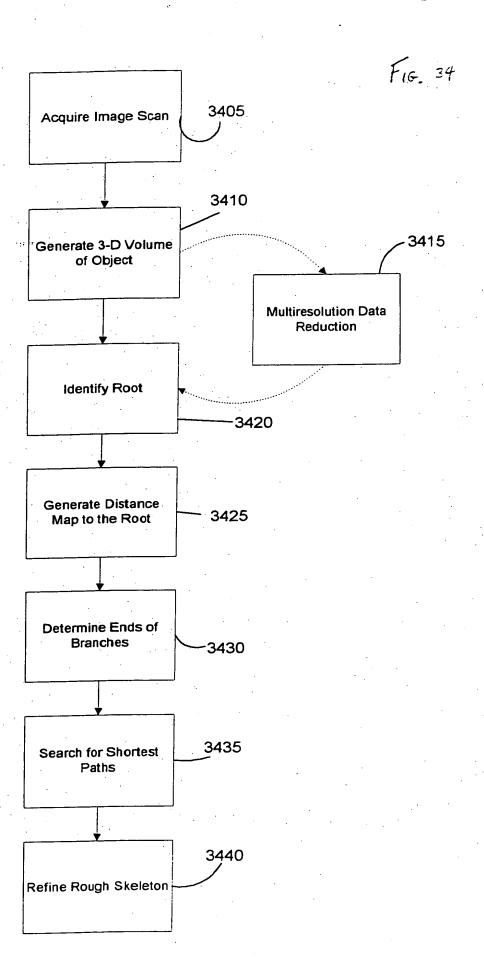
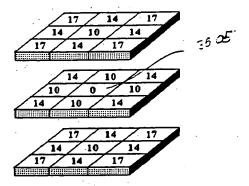


Fig. 35



F16. 36

```
1) Label root voxel with integer 0;
```

Else {

2) Construct a queue and line up the root in the queue;

end of calculating the distance map.

```
3) If( There is at least one voxel in the queue )
 Serve the voxel x on the top of the queue:
 For( each of x's 26-connected neighbor voxel y) {
     If (y in the volume and has not been labeled yet) {
         Line up the y in the queue;
         /* label the voxel y */
         Set dist = 999999;
         For( each of y's 26-connected neighbor voxel z ) {
            If (z) in the volume and has been already labeled with an integer of n, (z)
                 d_z \equiv n_z + d(y, z);
                 where d(y,z) is 10, 14 or 17 if the Euclidean distance between y and z is
                1,\sqrt{2}, or \sqrt{3}, respectively;
           If (dist > d_z) {
               label y with integer dist;
               disi = d_x;
x leaves the queue;
```